

# IQI 04, Seminar 4

Produced with pdflatex and xfig

- One qubit rotations.
- Universality for one qubit.
- State distinguishability for one qubit.
- Bra-ket notation.
- Application: Quantum cryptography.

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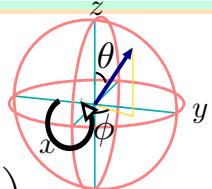


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## Rotations II

$$\alpha|0\rangle + \beta|1\rangle \cong e^{-i\phi/2} \cos(\theta/2)|0\rangle + e^{i\phi/2} \sin(\theta/2)|1\rangle$$



- $Y$ -rotations.

$$Y_\delta : \begin{pmatrix} \cos(\delta/2) & -\sin(\delta/2) \\ \sin(\delta/2) & \cos(\delta/2) \end{pmatrix}$$

$$\begin{array}{c} |0\rangle \\ |1\rangle \end{array} \xrightarrow{Y_\delta} \begin{cases} \cos(\delta/2)|0\rangle + \sin(\delta/2)|1\rangle \\ -\sin(\delta/2)|0\rangle + \cos(\delta/2)|1\rangle \end{cases}$$

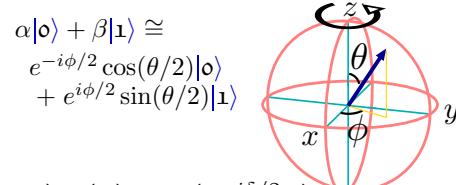
- $X$ -rotations.

$$X_\delta : \begin{pmatrix} \cos(\delta/2) & -i\sin(\delta/2) \\ -i\sin(\delta/2) & \cos(\delta/2) \end{pmatrix}$$

$$\begin{array}{c} |0\rangle \\ |1\rangle \end{array} \xrightarrow{X_\delta} \begin{cases} \cos(\delta/2)|0\rangle - i\sin(\delta/2)|1\rangle \\ -i\sin(\delta/2)|0\rangle + \cos(\delta/2)|1\rangle \end{cases}$$

## Rotations I

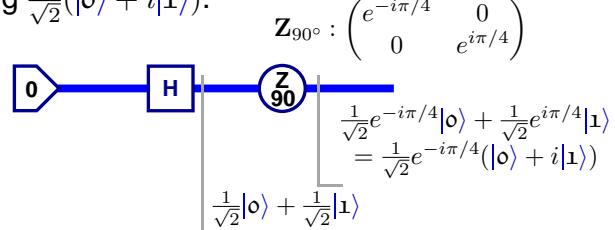
- Rotation gates rotate the state in the Bloch sphere representation.



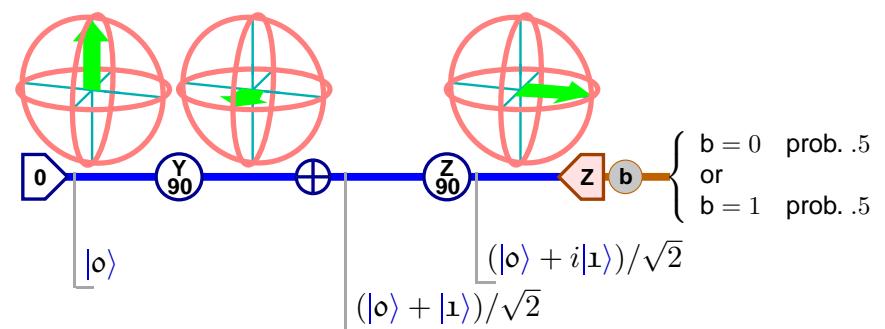
- $Z$ -rotations.

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} \xrightarrow{Z_\delta} \begin{pmatrix} e^{-i\delta/2} & 0 \\ 0 & e^{i\delta/2} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} e^{-i\delta/2}\alpha \\ e^{i\delta/2}\beta \end{pmatrix}$$

- Preparing  $\frac{1}{\sqrt{2}}(|0\rangle + i|1\rangle)$ .



## A One-Qubit Network



- What rotation should be added before the measurement to guarantee that  $b = 1$ ?



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## The Pauli Matrices

- Define the Pauli matrices by

$$\mathbb{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

- Rotations in terms of Pauli matrices.

$$\mathbf{x}_\delta = \begin{pmatrix} \cos(\delta/2) & -i \sin(\delta/2) \\ -i \sin(\delta/2) & \cos(\delta/2) \end{pmatrix} = \cos(\delta/2) \mathbb{1} - i \sin(\delta/2) \sigma_x$$

$$\mathbf{y}_\delta = \begin{pmatrix} \cos(\delta/2) & -\sin(\delta/2) \\ \sin(\delta/2) & \cos(\delta/2) \end{pmatrix} = \cos(\delta/2) \mathbb{1} - i \sin(\delta/2) \sigma_y$$

$$\mathbf{z}_\delta = \begin{pmatrix} \cos(\delta/2) - i \sin(\delta/2) & 0 \\ 0 & \cos(\delta/2) + i \sin(\delta/2) \end{pmatrix} = \cos(\delta/2) \mathbb{1} - i \sin(\delta/2) \sigma_z$$

- Relationship to the first set of gates.

$\sigma_z = \text{not} = i\mathbf{Z}_{180^\circ}$ .

$\sigma_x = \text{sgn} = i\mathbf{X}_{180^\circ}$ .

$\sigma_y = i\text{sgn.not} = i\mathbf{Y}_{180^\circ}$ .

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## Properties of Pauli Matrices

- Define the Pauli matrices by

$$\mathbb{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

- The Hermitian transpose of  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is  $A^\dagger = \begin{pmatrix} \bar{a} & \bar{c} \\ \bar{b} & \bar{d} \end{pmatrix}$ .

- $\sigma_u^\dagger = \sigma_u$ , that is, the Pauli matrices are *Hermitian*.

- $\sigma_u^2 = \mathbb{1}$ .

- The Pauli matrices *anticommute*:

$$\sigma_x \sigma_y = -\sigma_y \sigma_x, \sigma_y \sigma_z = -\sigma_z \sigma_y, \sigma_z \sigma_x = -\sigma_x \sigma_z.$$

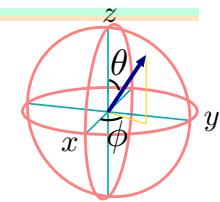
- The Pauli matrices form an operator basis:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \frac{(a+d)}{2} \mathbb{1} + \frac{(b+c)}{2} \sigma_x + \frac{i(b-c)}{2} \sigma_y + \frac{(a-d)}{2} \sigma_z$$

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## States and the Bloch Sphere

$$e^{-i\phi/2} \cos(\theta/2) |\mathbf{o}\rangle + e^{i\phi/2} \sin(\theta/2) |\mathbf{1}\rangle$$



- The *density matrix*  $\rho$  for state  $\mathbf{x} = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$  is

$$\rho = \mathbf{x}\mathbf{x}^\dagger = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} (\bar{\alpha}, \bar{\beta}) = \begin{pmatrix} \alpha\bar{\alpha} & \alpha\bar{\beta} \\ \beta\bar{\alpha} & \beta\bar{\beta} \end{pmatrix}$$

- $\rho$  represents the accessible information about the state.  
If  $\mathbf{y} = e^{i\delta} \mathbf{x}$ , then  $\mathbf{y}\mathbf{y}^\dagger = e^{i\delta} \mathbf{x} e^{-i\delta} \mathbf{x}^\dagger = \mathbf{x}\mathbf{x}^\dagger$ .

- Examples:

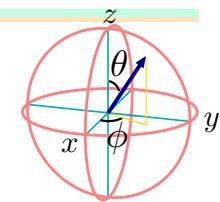
$$|\mathbf{-i}\rangle = \frac{1}{\sqrt{2}}(|\mathbf{o}\rangle - i|\mathbf{1}\rangle) \rightarrow \begin{cases} |\mathbf{o}\rangle & \rightarrow \frac{1}{2}(\mathbb{1} + \sigma_z) \\ |\mathbf{+}\rangle & \rightarrow \frac{1}{2}(\mathbb{1} + \sigma_x) \\ |\mathbf{-}\rangle & \rightarrow \frac{1}{2}(\mathbb{1} - \sigma_x) \\ |\mathbf{+i}\rangle & \rightarrow \frac{1}{2}(\mathbb{1} + \sigma_y) \\ |\mathbf{-i}\rangle & \rightarrow \frac{1}{2}(\mathbb{1} - \sigma_y) \end{cases}$$

$$\frac{1}{2} \begin{pmatrix} 1 \\ -i \end{pmatrix} (1, i) = \begin{pmatrix} 1 & i \\ -i & 1 \end{pmatrix} = \frac{1}{2} \left( \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \right) \\ = \frac{1}{2}(\mathbb{1} - \sigma_y)$$

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## States and the Bloch Sphere

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- $\rho$  represents the accessible information about the state.  
If  $\mathbf{y} = e^{i\delta} \mathbf{x}$ , then  $\mathbf{y}\mathbf{y}^\dagger = e^{i\delta} \mathbf{x} e^{-i\delta} \mathbf{x}^\dagger = \mathbf{x}\mathbf{x}^\dagger$ .

- $|\psi\rangle$  corresponds to  $\hat{u}$  on the Bloch sphere if and only if the density matrix  $\rho$  for  $|\psi\rangle$  is given by

$$\rho = \frac{1}{2}(1 + \hat{u} \cdot \vec{\sigma}) = \frac{1}{2}(1 + u_x \sigma_x + u_y \sigma_y + u_z \sigma_z)$$

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## The Density Matrix

- Let  $\rho$  be the density matrix for  $|\psi\rangle = \alpha|0\rangle + \beta|1\rangle$ .

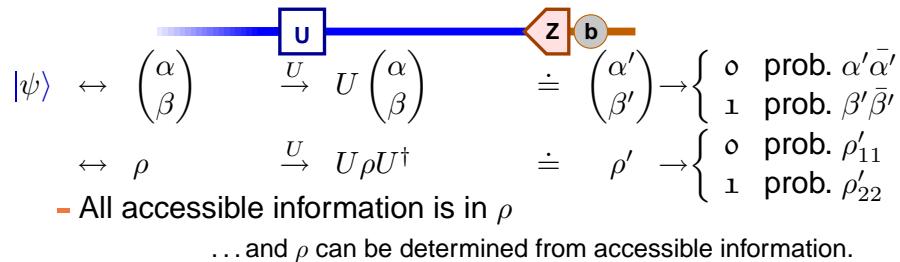
$$\rho = \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} = \begin{pmatrix} \alpha\bar{\alpha} & \alpha\bar{\beta} \\ \beta\bar{\alpha} & \beta\bar{\beta} \end{pmatrix}.$$

$\rho_{11}$  is the probability of measuring 0.

$\rho_{22}$  is the probability of measuring 1.

$$\text{tr}(\rho) = \rho_{11} + \rho_{22} = 1$$

- Accessible information. All information about  $|\psi\rangle$  is obtained by applying operations and measuring.



All accessible information is in  $\rho$

... and  $\rho$  can be determined from accessible information.

## More Conjugation

- 180° rotation around an arbitrary axis.

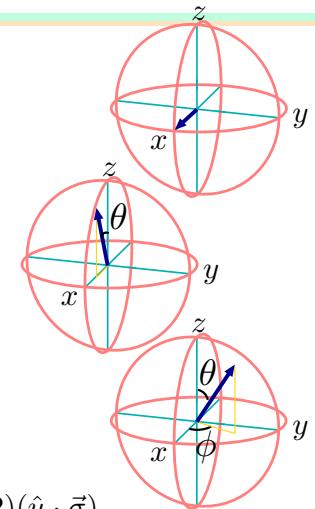
$$Z_{-\phi} Y_{90-\theta} X_{180} Y_{\theta-90} Z_\phi$$



$$Z_{-\phi} (\sin(\theta), 0, \cos(\theta))_{180} Z_\phi$$



$$(\sin(\theta)\cos(\phi), \sin(\theta)\sin(\phi), \cos(\theta))_{180}$$



- Rotation with axis  $\hat{u}$  by angle  $\delta$ :

$$\text{rot}(\hat{u}, \delta) = \cos(\delta/2)\mathbb{1} - i \sin(\delta/2)(\hat{u} \cdot \vec{\sigma}).$$

- Can implement any rotation with 5 major axis rotations.

... three are necessary and sufficient.

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## Conjugation

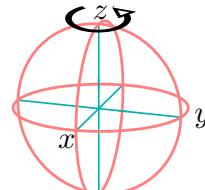
$$\rho \xrightarrow{U} U\rho U^\dagger$$

- Applying  $U$  conjugates density matrix  $\rho$  by  $U$ .

Example:  $U = Z_{90^\circ} = \frac{1}{\sqrt{2}}(\mathbb{1} - i\sigma_z) = \begin{pmatrix} e^{-i\pi/4} & 0 \\ 0 & e^{i\pi/4} \end{pmatrix}$ ,  
 $\rho = \frac{1}{2}(\mathbb{1} + \sigma_x)$ .

$$\begin{aligned} U\rho U^\dagger &= \frac{1}{2}(U\mathbb{1}U^\dagger + U\sigma_x U^\dagger) \\ &= \frac{1}{2}(\mathbb{1} + U\sigma_x U^\dagger) = \frac{1}{2}(\mathbb{1} + \sigma_y) \end{aligned}$$

- Simplify:



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## Universality for One Qubit

- Every unitary  $2 \times 2$  matrix is proportional to a rotation.

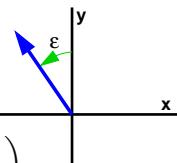
$$U = \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix}.$$

- May take  $u_{11}$  to be real.

- $U^\dagger U = \mathbb{1}$  implies  $|u_{11}|^2 + |u_{21}|^2 = 1$ : Write  $U = \begin{pmatrix} \cos(\delta/2) & u_{12} \\ e^{i\epsilon}\sin(\delta/2) & u_{22} \end{pmatrix}$

- $(\cos(\delta/2), e^{-i\epsilon}\sin(\delta/2)) \begin{pmatrix} u_{12} \\ u_{22} \end{pmatrix} = 0$ .

$$\begin{aligned} U &= \begin{pmatrix} \cos(\delta/2) & -e^{i\gamma}e^{-i\epsilon}\sin(\delta/2) \\ e^{i\epsilon}\sin(\delta/2) & e^{i\gamma}\cos(\delta/2) \end{pmatrix} \\ &= e^{i\gamma/2} \begin{pmatrix} e^{-i\gamma/2}\cos(\delta/2) & -e^{i\gamma/2}e^{-i\epsilon}\sin(\delta/2) \\ e^{-i\gamma/2}e^{i\epsilon}\sin(\delta/2) & e^{i\gamma/2}\cos(\delta/2) \end{pmatrix} \\ &= e^{i\gamma/2} \begin{pmatrix} \cos(\delta/2) & -e^{-i\epsilon}\sin(\delta/2) \\ e^{i\epsilon}\sin(\delta/2) & \cos(\delta/2) \end{pmatrix} \begin{pmatrix} e^{-i\gamma/2} & 0 \\ 0 & e^{i\gamma/2} \end{pmatrix} \\ &= e^{i\gamma/2}(\cos(\delta/2)\mathbb{1} - i\sin(\delta/2)(\cos(\epsilon)\sigma_y - \sin(\epsilon)\sigma_x))Z_\gamma \\ &= e^{i\gamma/2}Z_\epsilon Y_\delta Z_{-\epsilon} Z_\gamma \\ &= e^{i\gamma/2}Z_\epsilon Y_\delta Z_{\gamma-\epsilon} \end{aligned}$$



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